# Application of Mathematical Components to probabilities and program formalization 

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## This Talk

- We have been interested in applying formal verification to information security
- We have been led to look at topics such as information theory, error-correcting codes, probabilistic programs, etc.
- We would like to report on a few formal theories that might be of general interest
- The common topic is probability, the work spans several years
- Our message is that MathComp has been providing us with a reliable environment for our experiments


## Outline

Information Theory using MathComp

Monadic Equational Reasoning for Probabilistic Programs

Formal Semantics for Statistical Modeling

## SSREfLECT Early Adopters?

- Starting in 2004, we were working on formal proof of imperative programs in CoQ using separation logic
- We were facing productivity issues that we failed to analyze correctly
- By chance, we ran into

and realized that many of our concerns were addressed by SSREfLect


## SSREFLECT／MATHComp in Japan

1．We have been trying to promote MathComp in Japan with lectures
2．These lectures turned into a book in 2018


SSReflect／
MathComp
定理証明


3．In this book，tactics are given mascots，e．g．：
3.2 タクティク move＝＞，move：， move：＝＞，move／
タクティク move＝＞，move：はサブゴールとコンテキスト
間の型•変数•関数などを移動します（ $\rightarrow$ 表 3．2）。


## The SSReflect Zoo According to


elim
apply


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## Fundamental Questions Answered Information Theory

1. What is the ultimate data compression rate ${ }^{1}$ ?
2. What is the ultimate encoding rate ${ }^{2}$ for communication?

Setting:

- a source is a probability distribution
- a channel is a stochastic matrix (e.g., the binary symmetric channel $\left[\begin{array}{cc}1-p & p \\ p & 1-p\end{array}\right]$ )

Shannon answered the fundamental questions in 1948:

1. Source coding theorem: One cannot minimize the compression rate below the entropy
2. Channel coding theorem: One cannot maximize the encoding rate beyond the capacity of a channel
[^0]
## Information Theory: Basic Definitions [CT01]

- The entropy of a random variable taking $n$ values with probabilities $p_{i}$ is $H=-\sum_{i=0}^{n-1} p_{i} \log p_{i}$
- Given two probability mass functions $p$ and $q$, the divergence is $D(p \| q)=\sum_{x \in \mathcal{X}} p(x) \log \frac{p(x)}{q(x)}$
- The mutual information between two random variables $X, Y$ with joint probability mass function $p(x, y)$ and marginals $p(x)$ and $p(y)$ is $I(X ; Y)=D(p(x, y) \| p(x) p(y))$
- Consider an input $X$ and an output $Y$. A channel is a conditional probability distribution $p_{Y \mid X}(y \mid x)$. The capacity is $C=\max _{p(x)} I(X ; Y), p(x)$ ranging over all the input distributions
$\Rightarrow$ It looks like a good fit for SSREFLECT's iterated operators [BGBP08]


## Finite Probabilities with SSReflect and Coq

## (We are in 2009)

Finite probability theory with the iterated operators and the finite sets of MathComp and the real numbers of CoQ:

- Distributions over a finite type:

$$
\begin{aligned}
& \text { Record fdist (A : finType) }:=m k\{ \\
& f:>A->R+; \\
& \left.-: \backslash \operatorname{sum}_{-}(\mathrm{a} \text { in } A) \mathrm{f} a==1:>\mathrm{R}\right\} .
\end{aligned}
$$

- Probability of an event E given a distribution P:

```
Definition Pr P (E : {set A}) := \sum_(a in E) P a.
```

- Random variables:

```
Definition RV U T (P : fdist U) := U -> T.
```

- Distribution of a random variable $\mathrm{X}: ~ ` \operatorname{Pr}[\mathrm{X}=\mathrm{a}]$, shortcut for Pr P (X @ ${ }^{\wedge}-1$ : [set a]) or for fdistmap X P a


## Information Theory with MathComp

## Overview

Starting from:

- $H=-\sum_{i=0}^{n-1} p_{i} \log p_{i}$

```
    Definition entropy := - \sum_(a in A) P a * log (P a).
```

- $\sum_{x \in \mathcal{X}} p(x) \log \frac{p(x)}{q(x)}$

Definition div $:=\backslash$ sum_( a in A$) \mathrm{P}$ a $* \log (\mathrm{P}$ a / Q a).

- $D(p(x, y) \| p(x) p(y))$

Definition mutual_info := D(PQ || PQ`1 `x PQ`2).
We completely formalized an introductory textbook to information theory:

- Shannon's theorems [AH12, AHS14]
- Error-correcting codes (Hamming, BCH, Reed-Solomon, LDPC) [AG15, AGS20b]
- Presentations to information theorists [OHA14, AGS16, AGS18]



## Convexity of Information-theoretic Definitions

## Statements from [CT01]

Theorem
$H(p)$ is a concave function of $p$.


Entropy of a binary distribution
Theorem
$D(p \| q)$ is convex in the pair $(p, q)$, i.e., if $\left(p_{1}, q_{1}\right)$ and $\left(p_{2}, q_{2}\right)$ are pairs of probability mass functions, then

$$
D\left(\lambda p_{1}+(1-\lambda) p_{2} \| \lambda q_{1}+(1-\lambda) q_{2}\right) \leq \lambda D\left(p_{1} \| q_{1}\right)+(1-\lambda) D\left(p_{2} \| q_{2}\right)
$$

for all $0 \leq \lambda \leq 1$.
Theorem
Let $(X, Y) \sim p(x, y)=p(x) p(y \mid x)$. The mutual information $I(X ; Y)$ is a concave function of $p(x)$ for fixed $p(y \mid x)$ and a convex function of $p(y \mid x)$ for fixed $p(x)$.

## Convex Space

A convex space is a carrier together with a family of binary operators $a \triangleleft p \triangleright b$ with $0 \leq p \leq 1$ such that [Sto49, Fri09]:

- $a \triangleleft 0 \triangleright b=b$
- $a \triangleleft p \triangleright a=a$
(idempotence)
- $a \triangleleft p \triangleright b=b \triangleleft 1-p \triangleright a$
(skewed commutativity)
- $a \triangleleft p \triangleright(b \triangleleft q \triangleright b)=(a \triangleleft r \triangleright b) \triangleleft s \triangleright c$ (quasi-associativity)

$$
\text { with } \left.s=\overline{\bar{p}} \overline{\bar{q}} \text { and } r=\frac{p}{s} \text { (where } \bar{x}=1-x\right)
$$

Examples: real numbers $(p a+(1-p) b)$, functions to a convex space, finite distributions, etc.

Allows for generic definitions ( $U$ convex space, $V$ ordered convex space):

- $f: U \rightarrow U^{\prime}$ is affine $\stackrel{\text { def }}{=} \forall a, b, 0 \leq p \leq 1, f(a \triangleleft p \triangleright b)=f(a) \triangleleft p \triangleright f(b)$
- $f: U \rightarrow V$ is convex $\stackrel{\text { def }}{=} \forall a, b, 0 \leq p \leq 1, f(a \triangleleft p \triangleright b) \leq f(a) \triangleleft p \triangleright f(b)$
- also convex sets and hulls


## Convex Space in MathComp

Conveniently defined using Hierarchy-Builder [CST20]:

1. Declare an interface:
```
HB.mixin Record isConvexSpace (T : Type) := {
    _ <l _ |> _ : forall p, T -> T -> T ;
conv1 : forall a b, a < 1 %:pr |> b = a ;
convmm : forall p a, a <| p |> a = a ;
convC : forall p a b, a <| p |> b = b <| p. ~%:pr |> a;
convA : forall (p q : prob) (a b c : T),
    a <| p |> (b <| q |> c) =
    (a <| [r_of p, q] |> b) <| [s_of p, q] |> c }.
```

2. Declare a structure:
\#[short (type=convType)] HB.structure Definition ConvexSpace := \{T of isConvexSpace T \}.
3. Build instances: any lmodType (and thus real numbers), the type "fdist A", the type "A -> fdist B", etc.

## Application of Convex Spaces to Information Theory

- Short statements for convexity properties of information theoretic definitions:
- Lemma entropy_concave : concave_function (fun P : fdist A => 'H P).
- Lemma mutual_information_concave W :

```
concave_function (fun P => mutual_info (P `X W)).
```

where P ' X W is the product distribution $\lambda(x, y) . P x \cdot W x y$

- Lemma mutual_information_convex P :
convex_function
(fun W : A -> fdist B => mutual_info (P `X W)).


## Real Cones

A practical tool to reason about convexity

- In a convex space, quasi-associativity and skewed commutativity make for cumbersome symbolic computations
- It is actually possible to transpose such computations into real cones where addition is commutative and associative [VW06]:

```
HB.mixin Record isQuasiRealCone A := {
    addpt : A -> A -> A ;
    zero : A ;
    addptC : commutative addpt ;
    addptA : associative addpt ;
    addpt0 : right_id zero addpt ;
    scalept : R -> A -> A ;
    scale0pt : forall x, scalept 0 x = zero ;
    scale1pt : forall x, scalept 1 x = x ;
    scaleptDr : forall r, {morph scalept r : x y / addpt x y >-> addpt x y}
    scaleptA : forall p q x, 0<= p -> 0<= q ->
        scalept p (scalept q x) = scalept (p * q) x }.
HB.mixin Record isRealCone A of isQuasiRealCone A := {
    scaleptDl : forall p q x, 0 <= p -> 0 <= q ->
        scalept (p + q) x = addpt (scalept p x) (scalept q x) }.
```


## From Convex Spaces to Real Cones

Consider the following inductive type:
Inductive scaled (A : Type) := Scaled of Rpos \& A | Zero.
When A is a convex space:

- scaled A can be equipped with a real cone structure (take addpt (Scaled rex (Scaled q y) to be ( $r+q)\left(x \triangleleft \frac{r}{r+q} \triangleright y\right)$ )
- scaled A can be equipped with a convex space structure (take $x \triangleleft p \triangleright y$ to be addpt (scalept p x) (scalept (1-p) y) [VW06])

We can transpose symbolic computations using the fact that Scaled 1 is injective and affine:

- a <|p|>b
$\rightarrow$ Scaled 1 a <|p|> Scaled 1 b
$\rightarrow$ addpt (scalept p (Scaled 1 a)) (scalept (1-p) (Scaled 1 b)) where addition is associative and commutative

See Infotheo online or [AGS20a] for details

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## Monadic Equational Reasoning

This is an approach to verify programs with effects using equational reasoning [GH11]

- effects are represented by monad interfaces with typically:
- an operator (failure, arbitrary choice, probabilistic choice, etc.)
- rewriting laws in the form of equations
- monad interfaces can inherit from other interfaces and can be combined

Our starting idea:

- build a hierarchy of interfaces using packed classes [GGMR09]
- use SSREFLECT's rewrite [GT12] to perform equational reasoning


## Example of Monadic Laws

## Reminder

Monad laws (two operators: $r e t(\cdot)$ and $\cdot \gg \cdot)$ :

$$
\begin{aligned}
& \text { 1. } \operatorname{ret}(a) \gg f=f a \\
& \text { 2. } m \gg(\lambda x \cdot r e t(x))=m \\
& \text { 3. }(m \gg f) \gg g=m \gg(\lambda x \cdot f x \gg g)
\end{aligned}
$$

(left neutral)
(right neutral)
(associativity)

Arbitrary choice (one operator: $\cdot \square \cdot$ ):

1. $\left(m_{1} \square m_{2}\right) \square m_{3}=m_{1} \square\left(m_{2} \square m_{3}\right)$
(associativity)
2. $\left(m_{1} \square m_{2}\right) \gg=k=\left(m_{1} \gg k\right) \square\left(m_{2} \gg k\right)$
(left-distributivity of bind w.r.t. arbitrary choice)
etc.

## Functors and Monads with Hierarchy-Builder

- We consider CoQ's Type to be the category Set of sets and functions [TJ16]
- Let us start with functors:
- action on objects: F: Type -> Type (carrier)
- action on morphisms: actm below

```
HB.mixin Record isFunctor (F : Type -> Type) := {
    actm : forall A B, (A -> B) -> F A -> F B;
    functor_id : FunctorLaws.id actm ;
    functor_o : FunctorLaws.comp actm }.
```

- Next, monads (ret/bind interface):

```
HB.factory Record isMonad_ret_bind (F : Type -> Type) := {
    ret' : forall A, A -> F A ;
    bind : forall A B, F A -> (A -> F B) -> F B ;
    bindretf : BindLaws.left_neutral bind ret' ;
    bindmret : BindLaws.right_neutral bind ret' ;
    bindA : BindLaws.associative bind }.
```


## The Interface of the Probability Monad

Probability monad:

- extends the type of Monad
- similar interface to convex spaces
- with left-distributivity of bind w.r.t. probabilistic choice

```
HB.mixin Record isMonadProb (M : Type -> Type) of Monad M := {
    _ <l _ |> _ : forall p T, M T -> M T -> M T ;
    choice0 : forall T a b, a <| 0 |> b = b ;
    choiceC : forall T p a b, a <| p |> b = b <| 1 - p |> a ;
    choicemm : forall T p, idempotent (_ <| p |> _) ;
    choiceA : forall T p q r s a b c,
    p = r * s -> 1-s = (1 - p) * (1 - q) ->
    a<| p |> (b <| q |> c) = (a <| r |> b) <| s |> c;
    choice_bindDl : forall p a b,
    (a<l p |> b) >>= f = (a >>= f) <| p |> (b >>= f)}.
```


## Model of the Probability Monad

The interface do have an implementation

- Finite distributions do not form a monad because fdist : finType -> Type is not an endofunction
- Hence finitely-supported distributions with finmap [CS15]:

```
Record fsdist (A : choiceType) := mk {
    f :> {fsfun A -> R with 0} ;
    _ : all (fun x => 0 <b f x) (finsupp f) &&
    \sum_(a <- finsupp f) f a == 1}.
```

- The required operators $(\operatorname{ret}(\cdot), \cdot \gg \cdot, \cdot \triangleleft \cdot \triangleright \cdot)$ :
- fsdist1 : forall A : choiceType, A -> \{dist A\}

```
def}=[fsfun b in [fset a] => 1 | 0]
```

- fsdistbind : forall A B : choiceType, \{dist A\} -> (A -> \{dist B\}) -> \{dist B\}
$\stackrel{\text { def }}{=} \lambda b . \sum_{a \in \operatorname{supp}(d)} d(a) \times(f(a))(b)$ over $\bigcup_{x \in f(\operatorname{supp}(d))} \operatorname{supp}(x)$
- fsdist_conv : forall A : choiceType,

```
    prob -> {dist A} -> {dist A} -> {dist A}
```

$\stackrel{\text { def }}{=} \lambda$ a.p $d_{1}(a)+(1-p) d_{2}(a)$ over $\operatorname{supp}\left(d_{1}\right) \cup \operatorname{supp}\left(d_{2}\right)$

## The Start of a Hierarchy of Effects



Solid arrow: inherits
Dotted arrow: uses

## Probabilistic Program Verification using Rewriting

A biased coin with probability $p$ :
Definition bcoin $\{\mathrm{M}$ : probMonad\} p : M bool $:=\operatorname{Ret} \mathrm{T}<|\mathrm{p}|>\operatorname{Ret} \mathrm{F}$.

## Simple statement:

```
Definition two_coins p q : M (bool * bool) :=
    do a <- bcoin p; do b <- bcoin q; Ret (a, b).
Lemma two_coinsE p q : two_coins p q = two_coins q p.
```


## Proof:

```
rewrite /two_coins /bcoin.
    (Ret \(T<|\mathrm{p}|>\operatorname{Ret} \mathrm{F}) \gg=\)
    (fun \(\mathrm{a}=>(\operatorname{Ret} \mathrm{T}<|\mathrm{q}|>\operatorname{Ret} \mathrm{F}) \gg=(\) fun \(\mathrm{b}=>\operatorname{Ret}(\mathrm{a}, \mathrm{b}))\) )
rewrite ! [in LHS] (choice_bindDl, bindretf).
    (* choice_bindDl -> probability monad law *)
    (* bindretf \(=\) ret \(x>=f=f x \rightarrow\) monad law *)
    \((\operatorname{Ret}(T, T)<|q|>\operatorname{Ret}(T, F))<|p|>(\operatorname{Ret}(F, T)<|q|>\operatorname{Ret}(F, F))\)
rewrite -choiceACA.
    (* interchange <|p|> <|q|> -> real cones *)
    \((\operatorname{Ret}(T, T)<|p|>\operatorname{Ret}(T, F))<|q|>(\operatorname{Ret}(F, T)<|p|>\operatorname{Ret}(F, F))\)
```


## Examples Formalized with The Monae Library



- tree relabeling [GH11], Spark aggregation [Mu19b], Monty-Hall problem [GH11, Gib12]
- n-queens [GH11], completed by [Mu19a] (we fixed an earlier version of the latter)
- quicksort [MC20] (we completed a pre-existing formalization in Agda)
- Jaskelioff's theory of modular monad transformers [Jas09] (we actually proposed a fix for this theory)

Experiments documented in the following papers
[ANS19, AN21, AGNS21, SA22]

## Combination of Monad Interfaces Can be Difficult

It was observed in [ASCG16] that [GH11] contains a mistake ${ }^{3}$ :

- right-distributivity of bind over probabilistic choice $m \gg \lambda x .\left(k x \triangleleft p \triangleright k^{\prime} x\right)=(m \gg k) \triangleleft p \triangleright\left(m \gg k^{\prime}\right)$ combined with
- distributivity of probabilistic choice over arbitrary choice $m \triangleleft p \triangleright(a \square b)=(m \triangleleft p \triangleright a) \square(m \triangleleft p \triangleright b)$
result in a degenerated theory:
- distributivity of arbitrary choice over probabilistic choice $m \square(a \triangleleft p \triangleright b)=(m \square a) \triangleleft p \triangleright(m \square b)$
- which implies $a \triangleleft p \triangleright b=a \triangleleft q \triangleright b$ for all $p, q \in] 0 ; 1[$ [KP17, Thm A.3]
$\Rightarrow$ It is important to provide implementations for interfaces

[^1]
## Hierarchy of Effects (cont'd)



The probDrMonad adds:

- $m \gg \lambda x .\left(k x \triangleleft p \triangleright k^{\prime} x\right)=(m \gg k) \triangleleft p \triangleright\left(m \gg k^{\prime}\right)$

The geometrically convex monad adds:

- $m \triangleleft p \triangleright(a \square b)=(m \triangleleft p \triangleright a) \square(m \triangleleft p \triangleright b)$


## Model of the Geometrically Convex Monad

What is a computation in this monad?

- Gibbons observes that it should be a convex-closed sets of probability distributions [Gib12]
- Cheung provides a construction using adjunctions between categories [Che17]
We formalized Cheung's construction [AGNS21]:


This relies on an extension of Monae with concrete categories (to go beyond Set)

Ask Takafumi here in this room! $\rightarrow$

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## Statistical Model as Probabilistic Programs

- Example: guessing whether or not today's a weekday by looking at the number of buses passing by [Sta20]

```
normalize (
    let x = sample (bernoulli (2 / 7)) in
    let r = if x then 3 else 10 in
    let _ = score (r ~ 4 / 4! * e ~ (- r)) in
    return x)
```

- Intuitive explanation:
- sample takes a probability measure
- normalize returns a probability measure
- score ( $f$ x) means that we observe $x$ from the distribution corresponding to the density $f$
- here, observe 4 from the Poisson distribution

$$
\text { (of density } \frac{r^{k}}{k!} e^{-r} \text { ) }
$$

- Problem: existing formalizations in CoQ use axioms [HcS19, ZA22]


## Formalization of Kernels using MathComp-Analysis

Staton proposed a semantics for programs with sampling, scoring, and normalization using s-finite kernels [Sta17]
Definition:

- A kernel $X \leadsto Y$ is a function $k: X \rightarrow \Sigma_{Y} \rightarrow[0, \infty]$ such that

1. for all $x, k x$ is a measure
2. for all measurable set $U, x \mapsto k x U$ is measurable

Reminder: measure theory in MathComp-Analysis [AC22]

| measurable spaces |
| :--- | :--- |
| measure |
| measurable functions | | type measurableType |
| :--- |
| type \{measure set T -> \bar R\} |
| predicate measurable_fun |

Formal definition of kernel (notation R.-ker $\mathrm{X}^{\sim}>\mathrm{Y}$ ):
HB.mixin Record isKernel
X Y R (k : X -> \{measure set Y -> \bar R\}) :=
\{ measurable_kernel :
forall $U$, measurable $U$-> measurable_fun $\operatorname{set} T$ (fun $x=>k$ ) \}.

## S-Finite and Finite Kernels

## A circular-looking definition

Definition:

- A kernel $k: X \leadsto Y$ is finite when $\exists r$ s.t. $\forall x, k x Y<r$ (uniformly upper bounded)
- A kernel $k$ is s-finite when there exists a sequence of finite kernels $s$ such that $k=\sum_{i=0}^{\infty} s_{i}$

Circularity?

- s-finite kernels are more general than finite kernels (so they should be defined first)
- finite kernels are needed to define s-finite kernels...


## Wanted: Hierarchy of Kernels

To implement Staton's semantics of probabilistic programs


## S-Finite and Finite Kernels

## A recipe using Hierarchy-Builder

1. Interface for s-finite kernels using a predicate for finite kernels:
```
HB.mixin Record Kernel_isSFinite_subdef
    X Y R (k : X -> {measure set Y -> \bar R}) := {
    sfinite_subdef : exists2 s : (R.-ker X ~> Y)^nat,
    forall n, measure_fam_uub (s n) &
    forall x U, measurable U -> k x U = kseries s x U }.
```

Notation: R.-sfker $X{ }^{\sim}>Y$, inherits from R.-ker $X ~ ~>~ Y ~$
2. Interface for finite kernels:

HB.mixin Record SFiniteKernel_isFinite
X Y R (k : X $\rightarrow$ \{measure set Y $\rightarrow$ (bar R\}) :=
\{ measure_uub : measure_fam_uub k \}.
Notation: R.-fker $X{ }^{\sim}>Y$, inherits from R.-sfker $X ~ ~ X$
3. Definitive interface for s-finite kernels:

HB.factory Record Kernel_isSFinite
X Y R (k : X $\rightarrow$ \{measure set Y $->$ \bar R\})
of isKernel _ _ _ _ _ $\mathrm{k}:=\{$
sfinite : exists s : (R.-fker X ~> Y)^nat,
forall x U, measurable $\mathrm{U} \rightarrow \mathrm{k} x \mathrm{U}=$ kseries s x U$\}$.

## Composition of S-finite Kernels

The main property of $s$-finite kernels is that they are stable by composition (this provides a semantics for let $\mathrm{x}:=\mathrm{e}$ in $\mathrm{e}^{\prime}$ )

- Given $I: X \leadsto Y$ and $k: X \times Y \leadsto Z$, the composition $\sqrt{\beta} k$ is defined by

$$
\lambda x U \cdot \int_{y} k(x, y) U(\mathbf{d} / x)
$$

- Reminder: integral theory in MathComp-Analysis [AC22] | $\int_{x \in A} f(x)(\mathbf{d} \mu)$ | lint [mu]_(x in A) f x |
| :--- | :--- |
- Formal definition of composition:

```
Definition kcomp l k x U := \int[l x]_y k (x, y) U.
```

- Staton proved that the composition of s-finite kernels is a s-finite kernel [Sta17]. He skipped the proof that it is a kernel. It is not trivial but it can be achieved it by adapting existing lemmas from Fubini's theorem available in MathComp-Analysis.


## Semantics of Sampling using S-finite Kernels

## For illustration

What is the semantics of sample (bernoulli (2/7))?

1. Build the measurable space of probability measures pprobability Y R

- generated from the set of probability measures $\mu$ such that $\mu(U)<r$ for all measurable sets $U$ and $0 \leq r \leq 1$
- The type $\mathrm{X} \rightarrow$ pprobability $\mathrm{Y} R$ is essentially X -> \{measure set Y -> \bar R\}

2. $P$ : $X \rightarrow$ pprobability $Y R$ is a kernel

- for any measurable set $U$, fun $x=>P x U$ is measurable

3. $\mathrm{P}: \mathrm{X} \rightarrow$ pprobability $\mathrm{Y} R$ is a probability kernel

- because for all $x, P \mathrm{x}$ setT $=1$
- it is therefore automatically a s-finite kernel

4. For our example, take for $P$ the (constant) Bernoulli probability measure (built out of Dirac measures)

## Staton's Buses in Coq

```
normalize (
    let x = sample (bernoulli (2 / 7)) in
    let r = if x then 3 else 10 in
    let _ = score (r ^ 4 / 4! * e ^ (- r)) in
    return x)
```


## $\Downarrow$

```
Definition kstaton_bus : R.-sfker T ~> mbool :=
```

letin (sample (bernoulli p27))
(letin
(letin (ite var2of2 (ret k3) (ret k10))
(score (measurable_fun_comp mh var3of3)))
(ret var2of3)).
(* NB: density function parameterized,
"De Bruijn indices" for variables *)
Definition staton_bus := normalize kstaton_bus.

## Symbolic Evaluation of Statistical Models

We can evaluate a model to a distribution:
Lemma staton_busE P (t : R) U :
let $\mathrm{N}:=((2 / 7) *$ poisson4 $3+(5 / 7) *$ poisson4 10) \% R in
staton_bus mpoisson4 P t U =
( (2 / 7) \%: E * (poisson4 3) \%: E * \d_true U +
(5 / 7) \%:E * (poisson4 10) \%:E * \d_false U) * $\mathrm{N}^{\wedge}-1 \%$ :E.
(Proof by rewriting)
In mathematical notation:

$$
\frac{\frac{2}{7} \frac{3^{4}}{4!} e^{-3}}{N} \delta_{1}+\frac{\frac{5}{7} \frac{10^{4}}{4!} e^{-10}}{N} \delta_{0}=0.780369 \delta_{1}+0.219631 \delta_{0}
$$

So it is more likely that we are in the weekend

## Commutativity Property of Probabilistic Programs

## The main motivation for Staton's work

Is the following program transformation correct?
let $\mathrm{x}:=\mathrm{t}$ in
let $\mathrm{y}:=\mathrm{u}$ in

ret $(\mathrm{x}, \mathrm{y})$$\quad$| let $\mathrm{y}:=\mathrm{u}$ in |
| :--- |
| let $\mathrm{x}:=\mathrm{t}$ in |
| ret $(\mathrm{x}, \mathrm{y})$ |

This is a consequence of Tonelli-Fubini's theorem for s-finite measures:

```
(* \(f\) measurable non-negative, m1, m2 s-finite *)
Lemma sfinite_fubini :
    \int[m1]_x \int[m2]_y f (x, y) =
    \int[m2]_y \int[m1]_x f (x, y).
```

(This is a consequence of Tonelli-Fubini's theorem for $\sigma$-finite measures-the one you find in a standard undergraduate textbook on integration).

## Conclusion

The MathComp project has been providing us with

- good tactic support (e.g., rewrite in monadic equational reasoning)
- a rich, stable, flexible framework (we could combine MathComp and the CoQ standard library)
- libraries (finmap, MathComp-Analysis)
- methodologies (packed classes, naming conventions)
- tools (Hierarchy-Builder)
which let us
- develop original formalizations (InfoTheo, Monae)
- develop libraries for (probabilistic) program verification
- fix existing pencil-and-paper proofs
- retrofit results to MathComp (in particular MathComp-Analysis)
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[^0]:    ${ }^{1}$ compressed bitstring size / original message size
    ${ }^{2}$ original message size / encoded message size

[^1]:    ${ }^{3}$ We checked with MonaE that [GH11] was not relying on this mistake.

